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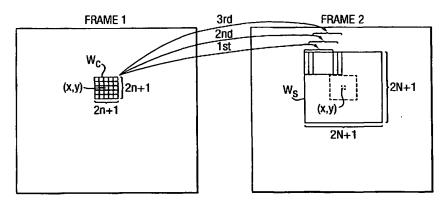
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[Continued on next page]

(54) Title: IMPROVEMENTS IN IMAGE VELOCITY ESTIMATION



(57) Abstract: A method of image velocity estimation in image processing which uses a block matching technique in which a similarity measure is used to calculate the similarity between blocks in successive images. The similarity measure is used to calculate a probability density function of candidate velocities. The calculation is on the basis of an exponential function of the similarity in which the similarity is multiplied by a parameter whose value is independent of position in the frame. The candidate velocities are thresholded to exclude those having a low probability. The value of the parameter and threshold are optimised together by coregistering all frames to the first frame, calculating the registration error, and varying them to minimise the registration error. The similarity measure is normalised with respect to the size of the block, for example by dividing it by the number of image samples in the blocks being compared. The similarity measure used may be the CD_{2-bis} similarity measure in which the mean and standard deviation of the similarity. This makes the similarity deviation of the two blocks being compared are adjusted to be the same before calculation of the similarity. This makes the similarity measure particularly suitable for ultrasound images. Further, block matching may be conducted across three frames of the sequence by comparing the intensities in blocks in the first and third, and second and third of the frames and finding the block in the third frame which best matches the block in the second frame and that block's corresponding position in the first frame.



WO 2004/052016 A3



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			PC . , GB 03/	05047	
A CLASSIF	CATION OF SUBJECT MATTER G06T7/20				
110 /	UUU177 EU				
Asserting to	International Patent Classification (IPC) or to both national classification	on and IPC			
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Category °	Citation of document, with indication, where appropriate, of the relev	varu passages		Relevant to dalm No.	
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	DULUTH, MA, US,	•			
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	page 154, left—hand column, line 13 — line				
	48				
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X Furt	ther documents are listed in the continuation of box C.	X Patent family	y members are listed	in annex.	
° Special ca	alegories of cited documents;	T' later document p	ublished after the int	emational filing date	
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]	European Patent Office, P.B. 5818 Patentiaan 2 NL - 2280 HV Rijswijk	_			
1	Tel. (+31-70) 340-2040, Tx. 31 651 epo nl, Fax: (+31-70) 340-3016	Chateau, J-P			

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		PC., 4B 03/0504/				
C.(Continuation) DOCUMENTS CONSIDERED TO BE RELEVANT						
Category °	Citation of document, with Indication, where appropriate, of the relevant passages	Relevant to claim No.				
A	COHEN B ET AL: "New maximum likelihood motion estimation schemes for noisy ultrasound images" PATTERN RECOGNITION, PERGAMON PRESS INC. ELMSFORD, N.Y, US, vol. 35, no. 2, February 2002 (2002–02), pages 455–463, XP004323385 ISSN: 0031–3203 cited in the application page 458, left-hand column, line 8 – line 18	1				
A .	US 4 667 233 A (FURUKAWA AKIHIRO) 19 May 1987 (1987-05-19) column 3, line 14 - line 62; figures 1,3	1				
A	WO 95/26539 A (REBERG JAN OTTO; AAGAARD MARTENS HARALD (DE); IDT DEUTSCHLAND GMBH (D) 5 October 1995 (1995-10-05) abstract page 12, line 25 - page 13, line 10					

tional application No. PCT/GB 03/05047

Box I Observations where certain claims were found unsearchable (Continuation of item 1 of first sheet)					
This international Search Report has not been established in respect of certain claims under Article 17(2)(a) for the following reasons:					
Claims Nos.: because they relate to subject matter not required to be searched by this Authority, namely:					
Claims Nos.: because they relate to parts of the International Application that do not comply with the prescribed requirements to such an extent that no meaningful international Search can be carried out, specifically:					
3. Claims Nos.: because they are dependent claims and are not drafted in accordance with the second and third sentences of Rule 6.4(a).					
Box II Observations where unity of invention is lacking (Continuation of item 2 of first sheet)					
This International Searching Authority found multiple inventions in this international application, as follows:					
see additional sheet					
As all required additional search fees were timely paid by the applicant, this international Search Report covers all searchable claims.					
2. As all searchable daims could be searched without effort justifying an additional fee, this Authority did not invite payment of any additional fee.					
3. As only some of the required additional search fees were timely paid by the applicant, this International Search Report covers only those claims for which fees were paid, specifically claims Nos.:					
4. No required additional search fees were timely paid by the applicant. Consequently, this International Search Report is restricted to the Invention first mentioned in the dalms; it is covered by claims Nos.: 1-17, 25-30					
Remark on Protest The additional search fees were accompanied by the applicant's protest. No protest accompanied the payment of additional search fees.					

FURTHER INFORMATION CONTINUED FROM PCT/ISA/ 210

This International Searching Authority found multiple (groups of) inventions in this international application, as follows:

1. claims: 1-17,25-30

A method of processing a sequence of image frames to estimate image velocity through the sequence comprising block matching using a similarity measure, calculating from the similarity meaure a probability measure that the two compared blocks are the same, and estimating the image velocity based on the probability measure, wherein the probability measure is calculated using a parametric function of the similarity which is independent of position in the image frames, corresponding apparatus claim and computer storage medium claim

2. claims: 18-20

A method of processing a sequence of image frames to estimate velocity through the sequence comprising block matching using a similarity measure by comparing the intensities in image blocks in three frames of the sequence by comparing the intensities in blocks in the first and third and the second and third of the three frames, and calculating the similarity between the said blocks on the basis of their intensities.

3. claims: 21-24

A method of processing a sequence of image frames to estimate image velocity through the sequence comprising: block matching using a similarity measure by comparing the intensities in image blocks in two frames of the sequence and calculating the similarity between the said blocks on the basis of their intensities, further comprising normalizing the intensities in the two blocks to have the same mean and standard deviation before calculating said similartity.

Int onal Application No
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